# Objective quality assessment of multi-channel noise reduction algorithms for hearing aids by means of psychoacoustic measures

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## Introduction

Modern hearing aids use microphone arrays for multichannel noise reduction. A well-known algorithm type is the beamforming which uses the spatial distribution of natural audio signal sources by evaluating the correlation properties between the microphone signals. For this, information about the direction of arrival of the target signal and the relative microphone positions are needed. Compared to single-channel envelope filtering algorithms beamformers in general lead to less target signal distortion at a high amount of noise reduction. Likewise, the human auditory system uses correlation properties between the audio signals at the left and right ear for object segregation (cocktail party effect). Therefore it is desirable to preserve the binaural information even after the noise reduction. In this study, different methods are shown and compared that preserve or reconstruct the binaural signal properties which is particularly important for head-worn binaurally connected hearing aids. Additionally, headshadow and diffraction effects have to be considered for the optimal design of the beamformer. The results show clearly, how the robustness of the noise reduction schemes is influenced under realistic signal conditions using different parameters and assumption about the sound wave propagation. The algorithms are evaluated using objective quality measures based on psychoacoustic models of the human auditory system.

#### Signal model and algorithms

The signals were recorded using two 3-channel behindthe-ear hearing aid shells mounted on a B&K dummy head. 6-channel head related transfer functions (HRTFs) in an anechoic room and real-world environmental noise in a cafeteria have been recorded. The input signal was composed from two directional signals filtered with HRTFs (target and interferer from 30° (front-left) and  $-135^{\circ}$  (back-right) azimuth, respectively) and mixed with the recorded cafeteria noise to generate a near-torealistic scenario. The 30° direction was chosen because it is asymmetric to the array and offers a more general assessment of the beamformers properties than a fixed 0° look direction.

The multi-channel algorithms used here are designed using the well-known constraint Minimum Variance Dis-



Abbildung 1: GSC beamformer and binaural post-filter

tortionless Response (MVDR) solution [4], Eq. (1),

$$W(f) = \frac{\Phi_{NN}^{-1}(f)d(f)}{d^{H}(f)\Phi_{NN}^{-1}(f)d(f)}$$
(1)

$$\boldsymbol{d}(f) = \begin{bmatrix} a_0 e^{j2\pi f\tau_0}, a_1 e^{j2\pi f\tau_1}, \dots, a_{M-1} e^{j2\pi f\tau_{M-1}} \end{bmatrix}^T$$

$$Y_f(f) = \boldsymbol{W}^{\boldsymbol{H}}(f) \boldsymbol{X}(f)$$
(3)

where f denotes the frequency, W the beamformer coefficients, d the propagation vector,  $a_m$  and  $\tau_m$  the amplitude and the group delay at microphone m, Xthe input vector,  $Y_f$  the output of the fixed beamformer (see Fig. 1). The blocks  $d^*$  and B denote the delay and amplitude compensation followed by a blocking matrix that filters out the target signal component. An adaptive filter  $H_{adapt}$  calculates a noise reference  $Y_a$ that contains the residual noise components that  $Y_f$  and X' have in common.

## **Binaural Outputs**

The binaural outputs are calculated using three different methods:

(i) (BIN\_PF) The binaural output is generated by a real-valued time-varying post-filter based on [2] that is controlled by the monaural beamformer output Z:

$$H_{\rm Bin}(t,f) = \frac{\left(|d_L(f)|^2 + |d_R(f)|^2\right)\Phi_{ZZ}(t,f)}{\Phi_{X_L X_L}(t,f) + \Phi_{X_R X_R}(t,f)}$$
(4)

$$Y_{bL}(t,f) = H_{\text{Bin}}(t,f)X_L(t,f)$$
(5)

$$Y_{bR}(t,f) = H_{Bin}(t,f)X_R(t,f)$$
(6)

where  $X_L, X_R$  (see Fig. 1) denote the input signals and  $d_L$ ,  $d_R$  the propagation vectors for the expected signal direction  $\theta_S$ , at the left and right reference microphone, respectively.  $\Phi_{ZZ}, \Phi_{X_LX_L}$  and  $\Phi_{X_RX_R}$  are the power

spectral density estimates for the signals  $Z, X_L, X_R$ , respectively. As the filter is real-valued, the phase of signal and noise are kept and therefore also most of the binaural cues. However, the envelope filter might introduce additional signal distortions.

(ii) (BIN\_PR) The monaural beamformer output Z is multiplied by the propagation vectors of the reference microphones which reconstructs only the interaural phase of the signal and may degrade spatial unmasking effects:

$$Y_{bL}(t,f) = d_L(f)Z(t,f)$$
(7)

$$Y_{bR}(t,f) = d_R(f)Z(t,f) \tag{8}$$

(iii) (BIN\_BL) The array is split into a subarray of two parallel 3-channel beamformers  $W_L$ ,  $W_R$  which use common information about the target direction and the noise field. This simulates the behavior of independent bilateral hearing devices and binaural cues may be distorted as described in [12]:

$$Y_{bL}(t,f) = Z_L(t,f) = W_L^H(f) X_{135}(t,f)$$
(9)

$$Y_{bR}(t,f) = Z_R(t,f) = W_L^H(f) X_{246}(t,f)$$
 (10)

where the numbers (1,3,5 and 2,4,6) refer to the microphones of the subarray, respectively.

## Results

The performance evaluation was based on three objective measures: The broadband Signal-to-Noise Ratio Enhancement (SNRE), the Perceptual Similarity Measure (PSM) from PEMO-Q [7] and the estimated Speech Reception Threshold (SRT) by [10]. A description of these measures can be found in [1]. Figure 2 shows the robust-

Algorithm	SNRE L dB	SNRE R dB	mean SNRE dB	PSM L	PSM R	SRT Gain dB
HM2_BIN_PF	9,0	10,9	10,0	0,69	0,61	8,4
HM2_BIN_PR	6,5	13,0	9,8	0,59	0,62	5,1
HM2_BIN_BL	4,4	4,6	4,5	0,56	0,31	4,8

**Tabelle 1:** Performance of different binaural stages for thefixed beamformer using propagation model HM2

ness of adaptive and fixed beamformers against steering errors assuming wave propagation models of different accuracy. In case of a perfect steering towards the target signal from  $30^{\circ}$  and a correct propagation model (at least a simple head model) the adaptive beamformers have a slightly higher performance. However, this performance gain might break down in case i) the target direction is not exactly known, ii) the target is moving too fast, iii) the hearing aid user moves his/her head.

#### Literatur

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**Abbildung 2:** Estimated SRT used as a performance and robustness measure for different algorithms and propagation models

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